

KEYENCE



More Speed. More Resolution. More Solutions.

Introducing the Most Versatile Machine Vision Systems in the Industry

VISION SYSTEM GENERAL CATALOG

The Evolution of KEYENCE Machine Vision Systems

KEYENCE has been an innovative leader in the machine vision field for more than 20 years. Its high speed and high performance machine vision systems have been continuously improved upon and now allow for even greater usability and stability when solving today's most difficult applications. The new CV-5000 Series is built upon years of experience and includes numerous innovations that have helped make KEYENCE a true industry leader. KEYENCE is committed to introducing new cutting-edge products that go beyond the expectations of its customers.

> CAD Series LED illumination units, lenses, etc.

The first image processing sensor.



VX Series







XV Series



CV-700 Series

1980s

General-purpose image processing device is developed.

1990s

KEYENCE becomes the first company in the industry to introduce complete, low cost visual inspection systems. These general purpose sensors created a new market for user friendly vision systems.

2000

KEYENCE introduces the industry's first 2 camera, built-in monitor, all-in-one compact vision solution.



Diverse lineup of machine vision equipment CV-5000 CV-2100 CV-2600 XV package general models CV-700 CV-500 CV-500 CV-100 VX

FUNCTION (Problem solving ability)

2003

High-speed general-purpose vision system incorporating twin processors and digital transfer camera is released.

2004

Package featuring 2 megapixels is released.

2005 to 2008

The CV-3000 and CV-5000 raise the bar for machine vision performance with 4 camera connectivity, unmatched speed, and the industry's most user friendly programming interface.

2009 and beyond

As the machine vision market expands, KEYENCE will use its vast experience and knowledge to continue to provide the industry with the most advanced technology available. **CV-5000 SERIES**

Product Overview

Ultra High-Speed, Multi-Camera Vision Systems

CV-5000 Series NEW > P.08

11x SMEGA eXpandable Courtector ACE Multi Courtector

Multi-Camera Series	⊳ P. 10
Expandable Controller Architecture	⊳ P. 13
Ultra High-Speed Processing and	
New Color Extraction Engine, A.C.E.II	⊳ P. 14
Defect Detection Solutions	⊳ P. 16
Statistical Processing and	
Communication Software	⊳ P. 23
Multiple Interface Options and	
Dimensions	⊳ P. 26

Wide array of inspection tools

CV-5000 Series models have a wide array of inspection tools to provide solutions to almost any inspection. These eighteen tools enable users to select the optimum inspection method, including the ability to set simultaneous inspections for a single trigger input.



All-in-One Image Processing

CV-700 Series \triangleright P.32





Detecting flaws or pinholes on sheet material



Detecting LCD segments

Features

- Advanced color Shade-Scale processing
- Controller with built-in monitor and 2-camera connection
- High-speed search and 360 degree rotation adjustment
- High-accuracy sub-pixel processing
- Large-capacity memory card available

Comprehensive menus

Menus are available for nearly every in-line need. Up to eight different inspection modes can be combined in a single program.

Presence/

Flaw detection





Point sensor









Center Pitch



Count



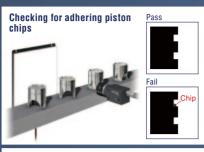


APPLICATIONS

INDEX

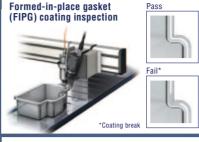
Applications

Part identification / Defect inspection



Inspecting motor wire bundles and checking





Camshaft mold cavity inspections

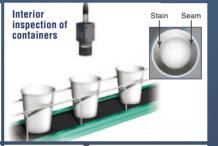


Food, Pharmaceutical & Others

Automotive / Metal







Detecting deformed cups

displaced cover



Measurement /





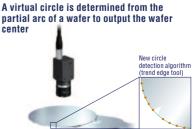
Label inspection (position/appearance)



Dimensional measurement of bottle rims







Electrical / Electronic



APPLICATIONS

HISTORY

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Automotive / Meta.

Food, Pharmaceutical

Å

Others

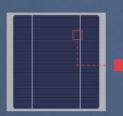
Electrical / Electronic

CV-5000 Series

The industry's most state-of-the-art problem solving tool is now even better. Introducing the new CV-5000 Series, relentless in its ability to solve challenging applications.

BEST RESOLUTION IN ITS CLASS Ultra high-definition image processing is now available for any production line 11x high-speed, 5 million-pixel camera $\frac{1}{2} \times \frac{5}{2} \times \frac{5}$

The 11x high-speed camera transfers ultra high-definition, 5 megapixel images (2432 x 2050 pixels) in 61.2 ms (16.3 times/sec). High-speed production lines can now harness the benefits of high-precision image processing. The new CV-5000 Series accepts up to four 5 million-pixel cameras and transfers the images simultaneously, enabling high-definition inspections of up to 20 million pixels.



Broken pattern detected in a solar battery electrode

- 1
_
- 1

Conventional 310,000 pixel-camera Defect cannot be recognized.



5 million pixel-camera The broken pattern is clearly visible.

FASTEST IN ITS CLASS High-speed, parallel processing system

3+1 processor technology 3+1 processor b P. 14

The 3 + 1 parallel processing architecture addresses the heavy processing needs required by high-volume 5 million pixel-images, color processing, and advanced algorithms that perform complex numeric operations.



WIDE RANGE OF CAMERA SELECTIONS

Users can select the camera best suited for the application

Fourteen different camera types $\beta = 11$

Users can select the optimum camera for their application from the industry's most extensive lineup of 5 million-pixel, 2 million-pixel, and ultra compact cameras. Each camera type is available in color or monochrome models. The CV-5000 Series can simultaneously run up to four different camera types making multi-camera applications more cost efficient.

INDUSTRY FIRST Controller-based illumination control

Introducing an expandable controller architecture



This architecture allows users to increase the flexibility of their systems using expansion units, which includes the camera expansion unit and the light control expansion unit. By limiting the functionality to the essentials, users can meet their requirements, reduce costs, and still maintain the flexibility to upgrade in the future.





CV Series Vision Systems

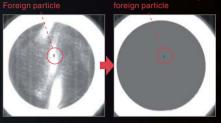
REST IN ITS CLASS Solutions for sophisticated defect inspection applications New defect detection algorithms for tackling difficult applications P.16

Several new algorithms have been added to detect foreign objects or burrs on irregularly shaped profiles. These new algorithms also filter out glare or other background noise so that only the flaws are emphasized.

Applications previously considered difficult



Detection of minute flaws along the profile



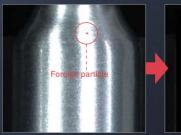
KEYENCE

COLOR CO

Particle detection on backgrounds with glare and other shade variations

BEST IN ITS CLASS Reliable detection under poor conditions New image enhancement processing > P. 15, 17

Significant advances were made to preprocessing functions that eliminate conditional changes caused by workpiece variation. The newly equipped Fine Color Processing function directly processes full-color information to reliably extract defects from backgrounds with pattern or illumination variations.



Foreign particle detection on a rounded metal surface



Isolates the foreign particles by cancelling out the metal reflections



Foreign particle detection on diagonal striped background

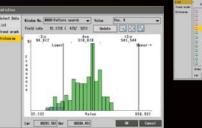
Removes the striped pattern and

reveals only the foreign particle

BEST IN ITS CLASS

Full range of statistical and image archive functions > P.23

CV-5000 Series controllers come with built-in statistical functions that let the user view the inspection results in realtime. The on-board image archive can store up to 1023 past inspection images that can be reviewed at a later time. Combining these two features allows for detailed analysis of product result trends and failure conditions, making it easier than ever for users to fine tune their program tolerance and settings to improve yield rates.





5 million-pixel, ultra high-speed cameras

FASTEST IN THE INDUSTRY

High-speed **5 million-pixel** camera series

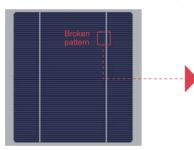


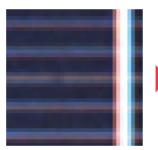
KEYENCE 11x high-speed cameras transfer 2432 x 2050 pixels in just 61.2 ms. This high-speed transfer rate delivers the benefits of high-definition image processing to high-throughput production lines. Now previously impossible inspections can be performed with a single camera. For example, it is possible to detect extremely minute defects on standard sized parts, or larger parts can be captured and inspected in detail with a single camera. In addition, the camera size is unobtrusive, making it easy to mount almost anywhere.



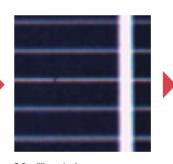
Reliably detect micro defects

Pattern breaks in solar battery electrodes





■ 310,000 pixels Lines are out of focus and cannot be detected.



■ 2 million pixels Broken pattern is out of focus and lacks clarity for an accurate inspection. The image requires a smaller field of view.



5 million pixels Lines appear sharp and the break can be accurately detected.

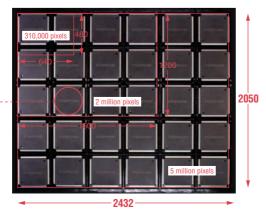
Capture the entire image in one shot with a wider field of view

Field of view comparisons with existing cameras

To maintain the resolution needed for print inspections...

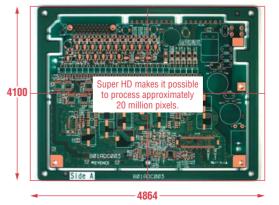
0609NX002

A 5 million-pixel camera can inspect the entire image at once while maintaining the resolution needed for inspection.



■ 20 million-pixel simultaneous process

Process up to 20 million pixels by connecting four 5 million-pixel cameras. All four cameras capture and transfer simultaneously.



HISTORY

[WIDE RANGE OF CAMERA SELECTIONS] Select the camera best suited for the application

The CV-5000 Series has a vast array of camera options to allow the user to carefully select the optimum camera based on their application needs. Whether the application calls for high precision color measurement with a 5 megapixel camera, ultra-fast processing with a 7x high speed camera, or mounting within a compact enclosure, the CV-5000 Series camera lineup can provide a solution.

7x high-speed cameras

The 7x CCD cameras of the CV-5000 Series are the fastest in their class, easily supporting high-speed lines and continuously moving targets. Images can be rapidly transferred without compression, solving inspection applications previously impossible with machine vision equipment. The 2 million-pixel camera models can complete processing in about the same amount of time as conventional 310,000-pixel models, enabling highresolution inspection without reducing product cycle times.

[FASTEST IN ITS CLASS] 2 million-pixel cameras NEW



[FASTEST IN ITS CLASS] ■ 310,000-pixel cameras For applications with priority on processing time. Transfers 640 x 480 pixels in 4.7 ms.



2x high-speed cameras

2 million-pixel cameras

Driven by a 2 million-pixel color CCD, these cameras transfer all 2 million pixels in 59 ms. Each model is highly effective for minute defect inspections, or dimension measurements that demand high-resolution.

Color type CV-200C Monochrome type CV-200M MEGA



∎ 310,000-pixel cameras

The 310,000-pixel cameras use a 2x high-speed progressivedrive CCD to enable transfer of 640 x 480 pixels (310,000 pixels) in 16 ms, supporting a wide range of applications.

Color type CV-035C Monochrome type CV-035M

HI-SPEED DIGITAL

DIGITAL



[SMALLEST IN THE INDUSTRY] Ultra-compact cameras

Compact cameras with the same high performance as other

CV-5000 Series cameras. Their small size enables installation in tight spaces normally reserved for photoelectric sensors. A 12-mm (0.47") wide, 310,000-pixel type and the industry's smallest 17-mm (0.67") wide, 2 million-pixel type are available. Different resolutions can be selected for different detection tasks. Side view attachments are also available.





DIGITAL

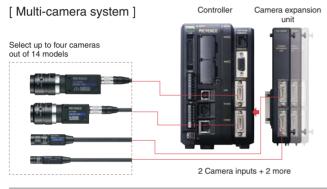
[INDUSTRY FIRST]

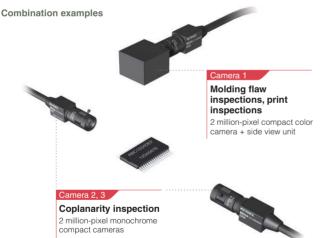


Simultaneous Acquisition Multi-Camera System

The CV-5000 Series allows simultaneous use of several different cameras selectable from a lineup of 14 different models. Users can select and combine the cameras best suited to the detection task, such as using a monochrome camera on camera 1 and a color camera on camera 2. Up to four cameras can be connected by adding the camera expansion unit.* The system runs all four cameras simultaneously (acquisition and processing), including the data-intensive 5 millionpixel color camera. The multi-camera system provides users with a flexible upgrade path to cope with future additions or changes in their inspection needs.

* The camera expansion unit can be connected to the CV-5702(P) and CV-5502(P)





When using multiple cameras to inspect simultaneously, the ability to select cameras best suited for the inspection provides cost efficiencies for the overall system.

[NEW] EtherNet/IP capable

It is possible to input/output values and controls by using the Ethernet port. Communication available via implicit and explicit messaging

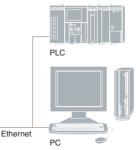
Up to 128 connected devices

I Meets Conformance Test A5 standards

Built-in Ethernet Port



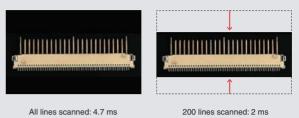




Partial image scanning

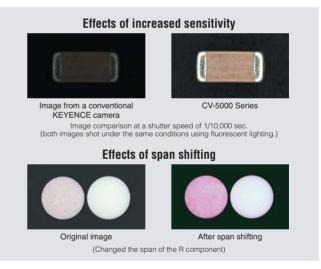
The Partial Image Scanning function significantly reduces image transfer time by transferring only the selected area of an image.

Image transfer time comparison: For the CV-H035C



Gain adjustments help increase contrast

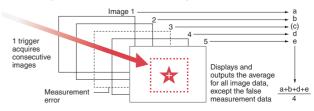
The CV-5000 Series controllers are equipped with a camera gain adjustment feature that allows up to 81 levels of sensitivity. When capturing images using high shutter speeds, an increased gain provides more light for brighter images without the need for costly strobe light equipment. Applying span offset processing, which also supports individual adjustments for the R, G, and B components of CCD data sampled at 10 bits, the shade difference in low contrast images is expanded and reliable image processing is possible.



Multi-image acquisition mode

This mode consecutively acquires and processes images using only a single trigger input. The data is averaged to provide consistent results for images that appear out of focus either due to the condition of the workpiece, or variation caused by vibration in the production line. A useful feature of this mode is the Exclusion function (patent pending) that removes false measurement data. (* The maximum and minimum values of the results after processing multiple images can also be output.)

[Processing method of the Multi-image acquisition mode]



New controller architecture achieves unparalleled functionality

Enhanced specifications at an efficient cost [WORLD'S FIRST]

"Expandable" controller architecture

The new CV-5000 Series offers two expansion units as add-ons to the main controller: a camera expansion unit and a light control expansion unit. This architecture allows users to control costs by selecting only units which are necessary without losing the flexibility to adapt to future changes.



Light control expansion unit

Camera expansion unit

Easily control lighting without extra wiring [WORLD'S FIRST]

LED light control expansion unit

Each light control expansion unit is equipped with two light terminals. The CV-5000 can control up to 4 expansion units allowing for a total of 8 lamps* to be utilized simultaneously. The controller's camera configuration menu has built-in dimmer controls and configurable lighting patterns. This provides users with complete control of

illumination without separate wiring and PLC-based programming. For example, it is possible to set a lamp to strobe with each trigger input, thus extending the life of the lamp. Light intensity can also be altered through the CV user interface and external command controls.

* As long as the total power consumption of the lamps does not exceed the rated power capacity, additional lamps can be connected by using the optional splitter cable. For example, the user can connect up to sixteen 10 W lamps

Application examples using the light control expansion unit

Lamp switching (multi-pattern lighting)

Simultaneous printing, dimensional, and orientation inspections

Low angle lighting is used for printing and dimensional inspections, while coaxial lighting is used to detect orientation. Each trigger input automatically switches between the lamps to perform all the inspections without using a PLC. Each setting can be programmed with up to four lighting patterns.

Light intensity presets for each program number

Automatic light intensity adjustment based on product

If the color and reflection ratios change based on the type of product being inspected, and if the product moves continuously without stopping, there may be no opportunity to adjust the light intensity without affecting the brightness of the acquired image. In this case, the desired light intensity level for each program number can be set so that it automatically changes based on the specific target properties. This will allow for uninterrupted changeovers without the need for manual adjustment



Light Intensity: 127 Color appears saturated on parts with high reflection ratio

Light Intensity: 80

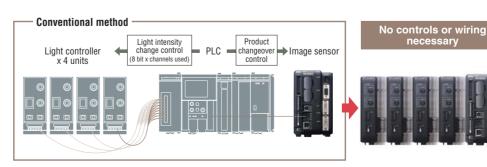
By presetting the optimum ht intensity for this product, the changeover is easily completed

No controls or wiring necessary

Product changeovers often require an adjustment in the light intensity to match the reflection properties of the product. Conventionally, this was done by a PLC which would change the light intensity settings on the light controller during product changeovers. However, with the CA-DC20E, it is possible to preset and register the appropriate light intensity for each inspection in the controller, without any extra wiring or complicated controls.

Coaxial lighting

the corners.



CV-5000 SERIES

Fastest processing platform in the industry

3 + 1 Processor System: Ultra high-speed, parallel processing

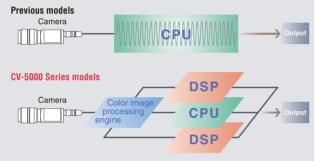
3-+1

CV-5000 Series models are driven by a high-speed color image processing engine (A.C.E. II). In addition, the high-speed RISC (Reduced Instruction Set Computer) CPU is supplemented by two DSP's (Digital Signal Processors) designed specifically for image processing. CV-5000 Series models use these four processors to attain

the fastest processing speed available in the industry. The CPU and DSP's are the latest technology, achieving twice the speed of the KEYENCE CV-3000 Series models.



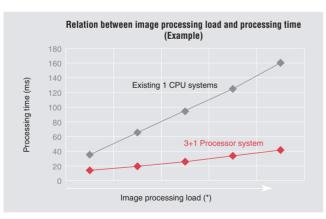
Comparison of processing by CV-5000 Series models and previous models



CV-5000 Series models share image processing tasks among multiple processors to achieve higher processing speeds.

Comparing the "3 + 1" processing system to a single CPU

The greater the image processing load (*), the more apparent the difference between the 3 + 1 parallel processing system and a single CPU system becomes. The 3 + 1 processing system is an example of the on-site stability concept of the CV-5000 Series. It allows users to optimize settings for stable performance in production-line environments without significantly increasing processing time.



* Image processing loads

The following factors increase image processing loads:

- Detailed parameter settings for searches and stain inspections
- Adding image enhancement functions
- I Increasing camera pixels

I Increasing inspection windows

■ High-speed processing examples

Chip component surface inspection

A CV-5000 Series model* completes processing with a 3-ms trigger interval.

Processing tasks

Using a 240 line partial image, the CV-5000 Series performs position compensation and color intensity processing while inspecting for defects, edge pitch, edge angle, and edge width.



Product cap surface inspection

A CV-5000 Series model* completes processing with a 12-ms trigger interval.

Processing tasks The 7x high-speed 310,000-pixel color camera captures full-screen images and carries out several product assessments. Defect inspection, difference processing (Pattern cancelling) color intensity processing, 360° rotary position compensation, and edge position compensation provide the most comprehensive and accurate inspection of products available.

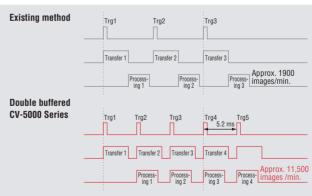


* CV-5500 combined with a CV-H035C

Double buffers

The CV-5000 Series models are equipped with double-buffered memory, allowing the unit to be triggered while processing the previous image. This allows for inspection times of 5.2 ms (approximately 11,500 images/minute) for full-screen image acquisition.

(* Assuming a 4-ms image processing time using the CV-H035C)



Fan-less design

In spite of the ultra high-speed processing, the CV-5000 Series models feature a fan-less design based on heat dissipation technology. A fan is a service-life component, and not using one translates into longer hours of reliable continuous operation. In addition, this design is particle emission-free, making the CV-5000 Series suitable for clean-room environments.

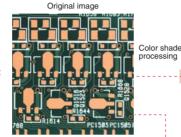
New color processing highlights difficult to see defects

[NEW]

New color extraction engine, A.C.E.II

The CV-5000 Series models are equipped with a new color extraction engine. The A.C.E.II (Advanced Color extraction Engine II) uses the HSB color model (closest color model to the human sensory system) to attain high color extraction performance that stabilizes previously unstable color processing schemes. CV-5000 Series models also feature "fine color processing" to extract color information exactly the way the camera captures it. This technology significantly broadens the range of color processing applications previously accomplished by machine vision systems.

> Extraction of copper foil on printed circuit boards



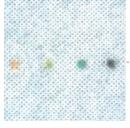
Color shade processing accurately distinguishes a specific color

Color shade processing can optimize the shade gradation using hue, saturation, and brightness. This makes it possible to convert images with low contrast into images with defined shade differences. Unlike conventional full color processing, which picks up all tone changes and makes pass/fail distinction difficult, color shade processing can optimize the shade difference between a user-specified color and the background.

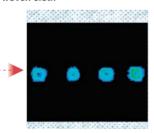
Fine color processing Detects all color variations

Fine color processing directly processes full color information exactly as the color camera captures it. This is ideal for detecting flaws on sheets, films, and non-woven cloths where the flaw can appear in any color with respect to the background. No setup is required for color extraction, allowing users to complete the inspection with one simple operation.

Foreign particle detection on a non-woven cloth



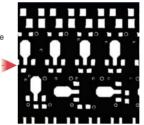
Original image



Shade differential display Reliable extracts all colors.

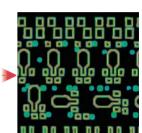


The newly added Intensity Cancellation function solves a common problem of detecting changes when using full color processing on color images. This function delivers stable detection performance to field applications by ignoring glare and lighting variations on the target background, and detecting only the area where hue and saturation differences exist.

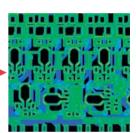


Color shade display A.C.E.II selects the copper color and blackens the area around it

Standard color processing



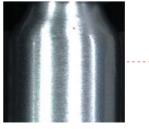
Shade differential display A.C.E.II accurately extracts only the copper foil portions.



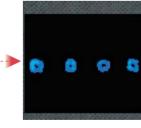
Standard extraction display Conventional processing captures all tone changes, rendering any distinction of the copper foil and its surrounding components impossible.



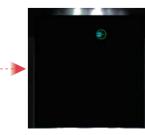
Background is darkened



Workpiece with varying lighting conditions



Reliably extracts all colors.



Detects only the defect

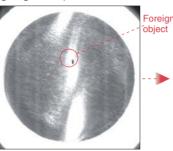
Surface defect detection

KEYENCE Machine Vision Systems have continually evolved by providing reliable solutions to inspection challenges. We have devoted countless hours of research and development to provide inspection solutions that represent the most demanding requirements. The CV-5000 Series models are equipped with advanced defect detection algorithms that eliminate many of the instabilities normally associated with surface appearance inspections.

Isolates defects for detection on shaded backgrounds [FIRST IN ITS CLASS] Real-time shade correction (patent pending)

Real-time shade correction isolates defects, even when the background has shadow-like gradations. This filter enables inspections not possible before by cancelling shadows that even lighting techniques could not

remove. Unlike commonly used shading correction filters that apply the same correction to all images, this correction adapts in real time to constantly changing shades.



Original image Inspections are difficult due to inconsistent glare on each workpiece.

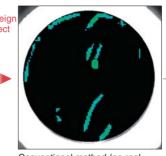
Application Example: Surface inspection of curved surfaces on metal



Normally, the dent in this image could not be detected because of the random glare and granular texture of the metal.



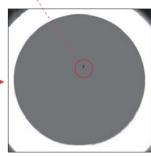
The image enhancement filter extracts only the dent.



Conventional method (no realtime shade correction, stain mode stability display) Erroneously detects areas of glare as

Erroneously detects areas of glare as defects.

Accurately extracts only the foreign object



Real-time shade correction Shaded areas on the background are cancelled, revealing only the foreign object. Repeatedly extracts only the foreign object, even if the glare has a different shape for each image.



The same workpiece with a line-like scratch.



Cancels glare and isolates the scratch.

Powerful features for detecting burrs or flaws on profiles [FIRST IN ITS CLASS] Trend Edge Defect Detection (patent pending)

This tool extracts the profile from the edge of a workpiece and uses it to recognize large differences such as burrs or flaws. In addition to geometrical shapes such as circles and straight lines, the tool also recognizes complex contours, such as ovals and free-form curves.

Detecting burrs and flaws in resin molded parts

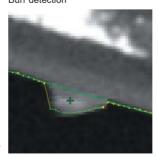
Profile trace image

Trend edge detects the profile of the workpiece and automatically generates reference model lines (the green line in this image) consisting of free-form curves.



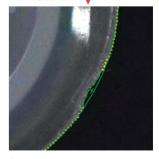


Burr detection



The burr generates a difference in the distance from the reference line, which allows the tool to detect it.

Flaw detection



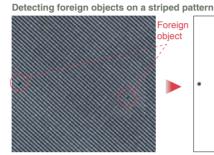
The tool reliably detects even the most subtle nicks along the profile, a defect otherwise considered difficult to detect.

The CV-5000 Series features 18 preprocessing filters that highlight otherwise obscure defects. Users can combine up to 13 preprocessing filters in a single window.

NEW

Softening filter (patent pending)

Softening reduces fine patterns and noise in the background. The softening effect is individually adjustable in the X and Y directions. This filter can be applied to a wide range of applications, including part counting inspections.



Original image This inspection would have been impossible because of the diagonal stripe pattern.

Differential inspection

The differential process inspects defects by ignoring patterns in the background. Users can choose from two processing methods to suit the application.

Differential processing with a registered image

This method extracts only the differences found by comparing the acquired image to a preregistered master image. The level of difference that determines a defect is adjustable to account for individual part variation.

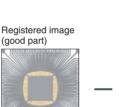
Real-time differential processing

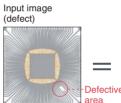
This method analyzes acquired images in real time. The process ignores the background and searches for minute variations within the image, without using a master image.



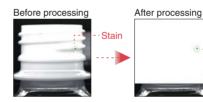
Softening filter + real-time shade correction Striped background removed, allowing

extraction of only the foreign objects.





Only the defective area is extracted, even on objects with complex shapes such as leadframes.





Differential image



Extracts only the defective area

Ignores the profile

of the bottle and

detects only the stain

Inspecting bottle openings

Reliably captures burrs and flaws along distorted circles and freeformed lines.



Enlarged image

Stable detection, even when the camera is mounted at an angle.

CV Series Vision Systems 17

Introducing the newest standard in surface inspection [MOST POWERFUL IN ITS CLASS] Stain inspection tool

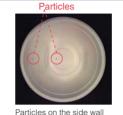
The Stain inspection tool searches for scratches and stains by comparing them against the surrounding shade level. Compared to binary processing, this mode has greater tolerance against varying conditions, making it ideal for surface inspections on production lines where individual variation of parts and light intensity fluctuations otherwise present problems. The defect distribution display allows optimized tuning by providing a quick visualization of how the image processor sees the defect.

Defect Distribution Display Function [patent pending]

Using the colors blue, green, yellow, and red, the defect distribution display assigns a color to defects according to the intensity difference between it and the surrounding area. This provides a visual understanding of the difference between intended and unintended defect regions

Relation between stability display color and stain level (guideline)



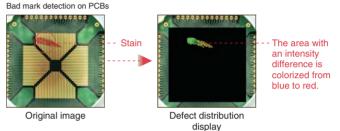


and bottom of a container



Conventional binary processing would not be able to detect these particles because of the lack of contrast between the particles and the dark portions inside the container

However, stain inspection mode ignores the differences in the shade, allowing reliable detection of the particles.



The defect distribution display appears in real-time so that users can intuitively maximize the difference between intended and unintended areas of inspection.

The algorithm of the stain inspection tool equipped on the KEYENCE CV Series.

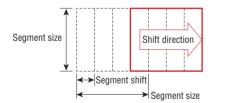
Average

intensity

①95

Stain extraction method

① The stain inspection tool measures the average intensity of specified areas (segments) and then shifts by 1/4 the area of the segment size

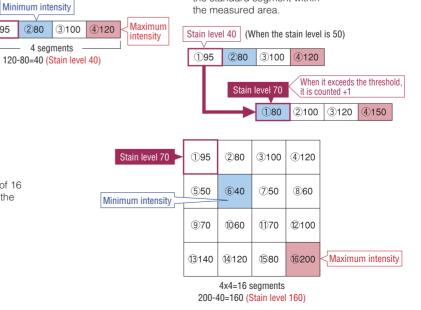


2 It determines the difference between maximum and minimum intensity of 4 segments, including a standard segment (195 in the figure below). The difference is considered the stain level of a standard segment.

(2)80

3 When the stain level exceeds the preset threshold, the standard segment is counted as a stain. The number of times the preset threshold is exceeded in a measured area is called the "Stain Area".

It repeats 1 to 3 constantly shifting the standard segment within the measured area.



When X and Y directions are specified as the detection direction

The difference between the maximum and minimum intensity of 16 segments in both the X and Y directions are calculated using the standard segment as a reference.

Measurement Solutions

Measure profiles using only a single inspection tool [MOST POWERFUL IN ITS CLASS] Trend Edge Function (patent pending)

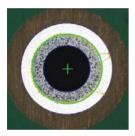
The Trend Edge tool detects edges at user-specified distances within the inspection area, and outputs the max, min, and average of all the data from each measured point. Previously, this required multiple windows and calculation settings, but now the same inspection can be done by configuring a single inspection setting. The measurements obtained can also be used to draw approximated lines and virtual circles.

Inspection theory

Trend edge detects the width and position of edges while moving across narrow segments at fine pitches.

- To increase position detection accuracy --- make the segment size smaller.
- To reduce processing time increases the shifting width (travel distance)
- within the segment Trend direction refers to
- -- the direction to move within the segment

■ Circle Detection function



Detecting through-hole centers

Edge detection direction

Trend edge can calculate the center and diameter of a hole by drawing a virtual circle along multiple edge positions around a through hole. Abnormal edge positions are removed before drawing the virtual circle to allow for reliable measurements

Trend direction

Segment shifting width

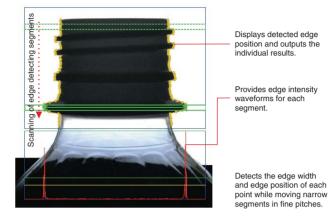
Detected edge (max.)

Detected edge (min.)

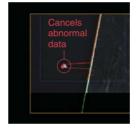
Measurement area

Work under measurement

Segment size



Line Detection function



Detecting the position of glass substrate edges

Trend edge can draw a virtual straight line along edge positions of a substrate's edge. As with the circle detection, line detection also cancels abnormal edge positions

Measure a variety of geometric shapes [MOST EXTENSIVE IN ITS CLASS] Geometric dimensional measurement

CV-5000 Series models can measure a variety of geometric dimensions based on position data obtained through edge detection and pattern searches

Measureable items

a 5 megapixel camera.

(repeatable accuracy) $= \pm 1 \ \mu m \ \pm 0.04 \ Mil$)

• 2-point distance • Angle of line between 2 points • Circle radius • Circle center

Measure dimensions with even greater accuracy by using

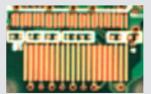
Assuming a 50-mm 1.97" field of view in the X axis -> approx. repeatability accuracy ±1 µm ±0.04 Mil (Typical example, FOV of 50 mm 1.97" ÷2430 pixels x ±0.05 pixels

- Average angle Lines Intersections Point-to-line distance Line angle
- 2-line intersection Perpendicular line between points and lines Bisect

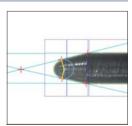
· Middle point



Measures concentricity and angles formed by lines through the centers of the large and small holes.

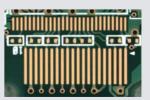


Enlarged image using a 310,000-pixel camera Enlarged image causes blurry edges, rendering the target unsuitable for precision measurements.



Dimensional measurement of a metal part

Measures tip radius, angle, and outer diameter.



Enlarged image using a 5,000,000-pixel camera Profiles in the object are crisp allowing precision measurements

Character Recognition

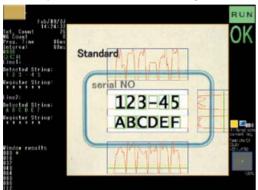
Other Inspection Tools

OCR Function

CV-5000 Series models are OCR capable. Simply register the characters and specify the area of inspection. OCR supports alphanumeric, user-defined characters, and also features an automatic calendar for date and lot number inspection without daily registering or setting changes.

Printing inspection for consumption dates

Automatically extracts one character at a time to recognize characters



Automatic calendar support

Provides functionality of dedicated OCR devices such as offsetting, tolerance adjustment, and zero-suppressing.

Selectable extraction method

Allows selection between automatic or fixed extraction. Automatic extraction also features a user-specified extraction ratio.

Batch library registration screen



NEW Date encryption support
 Recognizes and determines pass/fail of

encrypted dates by converting characters according to an encryption table.

Recognition level reporting

Outputs character recognition level per character for quick identification of print quality problems.

Allows registration of 20 user-defined characters (symbols, etc.), in addition to standard alphanumeric characters.

Effortless registration simultaneously saves characters in the program library.

Examples of reliable detection by using preprocessing filters

The differential filter and color shade processing can be used to isolate the background from the printing. This allows reliable inspection even when the background changes.

Original image

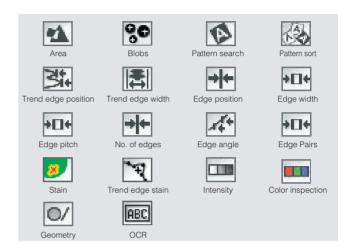




Cancels background to isolate printing.

Wide array of inspection tools (Eighteen tools)

CV-5000 Series models have a wide array of inspection tools to provide solutions to almost any inspection. These tools enable users to select the optimum inspection method, including the ability to set simultaneous inspections for a single trigger input.



Typical inspection tools

Color inspection

Distinguishes colors by digitizing hue, saturation, and brightness for greater color-detection accuracy. Unlike conventional color detection where color is distinguished by the size of the extracted area of color, the CV-5000 Series models actually reference the digital value.

Part count

Counts parts by using the blob tool allowing inspection of the center point, perimeter length, and circularity of each part found. LED lighting inspection



Counting terminals



Other Features

Conditional branching Each inspection window can be configured to execute based on the results of another window or numeric operation.

Auto-adjusting inspection areas Inspection areas (rectangles, circles) can be created in real-time with edge position detection or numeric operations.

Individual triggers, strobe light support

Individual trigger input allows sequential image acquisition using multiple cameras. Individual strobe outputs are also supported. Command memory

Features memory for 1,000 commands. The memory is programmable during operation by an external input or the console, and can be referenced by numerical operations.

Scaling Pixels can be scaled to the dimensions of the field of view.

Compatibility with CV-3000 Series settings

Setting files for our CV-3000 Series are upward-compatible.

Reliable and Easy On-Site Operation

Reduces light disturbances for highly reliable inspections

Automatically corrects for variations in light intensity in order to provide consistent illumination.

By saving a reference image acquired under optimal lighting conditions, the controller can monitor the light intensity each time it acquires and processes an image. An automatic digital gain adjustment corrects the light intensity to match the original reference image for less measurement variation over the life of the light source.

Reference image



The light intensity of this image becomes the reference. By registering it before the inspection, the controller can correct the light intensity for images that deviate from this reference by a given amount.

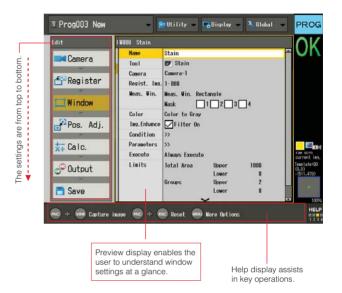


The acquired image before correction.

Based on the difference in light intensity detected in the acquired image compared to the registered reference image, the controller corrects the light intensity within the inspection area

KEYENCE Vision Flow menu

KEYENCE has further improved its vision flow menu to ensure a userfriendly setup. This intuitive menu flows from top to bottom, guiding users through the simple setup procedures.



Wide array of image enhancement filters

CV-5000 Series controllers are loaded with a wide array of filters to remove noise and isolate or otherwise enhance detection areas. In addition to the Expansion, Shrink, and Sobel filters, a total of 18 filters can be used, including preprocessing filters for binary color conversion and color shade processing.

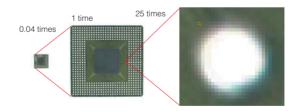


Binary	-	Detail
Expand	•	Detail
Shrink	Ŧ	Detail
kverage	•	Detail
Median	Ŧ	Detail
Sharpen	•	Detail
Sobel X	•	Detail
Sobel Y	¥	Detail
Sobe I	•	Detail
Prewitt	¥	Detail
Laplacian	•	Detail
Contrast Conv.	•	Detail
Img Extraction	•	Detail

Apply 13 layers out of 18 available filters in any combination.

Zoom Display function

The Zoom Display function enables users to continuously zoom the display screen from 0.04 times to 25 times. This function can be used regardless of the operation status or programming menu.



Other functions

Image capturing

Allows on-demand image capturing to the removable SD memory card (bitmap format).

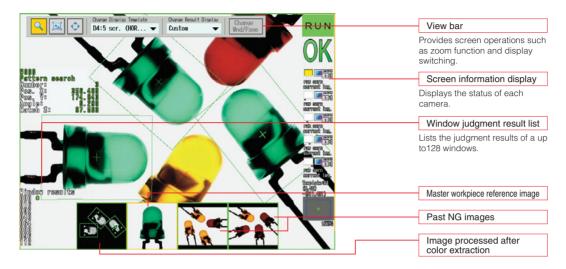
File management Allows users to copy files on the SD card or format a new card without using a PC.

I/O communication monitor Displays the I/O signal status during setup and operation.

Operator-friendly display options

SVGA monitor output

KEYENCE has adopted a high-resolution SVGA (800 x 600 pixels) monitor output for superior image quality. This function enables the user to quickly monitor the operational status of the inspection at an extensive level. Multiple inspection images can be monitored simultaneously, eliminating the need to switch the screens on the remote console.

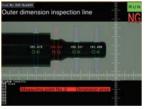


Selectable screen display formats NEW

Choose from nine available screen display formats to match the user's application needs. Display cameras and display contents can be chosen per screen, making it possible to view current images on the main screen while viewing past NG images and registered images on subscreens.

Custom Display function NEW

The Custom Display function enables flexible creation of user-defined displays such as the judgment results or measured values of only specified inspection windows. With this function, the user can also create and display custom text and graphics.



Example of custom display

Administrator mode/operator mode (password enabled)

The administrator mode/ operator mode enables management of operational changes with the use of passwords. This prevents unauthorised changes to the system. Combining this function with the custom menu permits only specific functions to be accessed in operator mode.

Custom menu NEW

The custom menu displays only necessary menu items. For example, the normal menu view can be reduced to only display settings for color extraction and limit setup. This will help to simplify programming and prevent unauthorised system tampering.



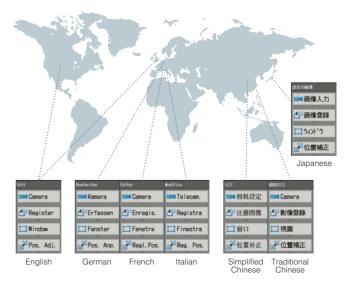


In the past, it was possible to alter all the items in setting menus. For this reason, there was a risk that unauthorised users might alter items mistakenly.

After the display menu is customized, only the items required for daily operation are displayed, so operators can easily understand the settings. This reduces the risk that operators will perform an incorrect operation.

Multi language support NEW

Multi language support in 7 languages: English, German, French, Italian, Simplified Chinese, Traditional Chinese, and Japanese.



Powerful troubleshooting tools

Statistical processing

The Statistical function enables the user to store up to 20,000 points of measurement data in the internal memory of the unit and easily check the maximum value, minimum value, average value, standard deviation, NG count, and yield, all without having to connect to an external PC. This function also enables the user to display trend graphs and histograms and make on-the-fly changes to limits based on the results of the gathered data. Up to 1023* previously captured images can also be accessed directly on the graph. (*using the CV-035M or CV-S035M).

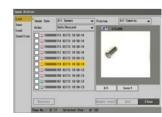


[BEST IN ITS CLASS] Image Archive and Retest function

The Image Archive function saves inspected images to the internal memory or a memory card. With this function, the previously failed images can be viewed during operation. The saved images can also be retested using new settings to verify proper operation of any adjustments made to the program.

Maximum image storage capacity per camera*

Type of camera	Main unit memory	4 GB SD card
Monochrome 240,000 pixels	1,023 images	15,314 images
Color 240,000 pixels	1,020 images	5,328 images
Monochrome 310,000 pixels	511 images	12,367 images
Color 310,000 pixels	509 images	4,265 images
Monochrome 2,000,000 pixels	127 images	2,077 images
Color 2,000,000 pixels	124 images	696 images
Monochrome 5,000,000 pixels	50 images	808 images
Color 5,000,000 pixels	47 images	270 images



* For images saved to the main unit memory on the CV-5702(P), the number of images indicates the representative values when the number of cameras to be connected is 1 and the accumulation condition is "all". For images saved to the 4GB SD card, the number of images indicates the representative values when the number of cameras to be connected is 1.

CV-5000 SERIES

Real time data acquisition with PC Simulator

MULTI-LINE DATA ACQUISITION

KEYENCE unique software packages offer simultaneous real-time data acquisition of both measurement results and captured images from up to 8 controllers. The following versions of CV-H software are available:

- 1. CV-H1NE Dedicated data acquisition software for CV-2100(P)
- 2. CV-H3N Dedicated data acquisition software for CV-3002(P)/3502(P) with optional PC Simulator function
- 3. CV-H5N Dedicated data acquisition software for CV-5002(P)/5502(P)/5702(P) with optional PC Simulator function

Data and image collection

Measurement values collected on the CV controller can be output via RS232, Ethernet, or USB.

The acquired data can be simultaneously displayed and saved onto an external hard drive.

Captured images that are transferred to a PC can be sorted by their OK/NG status based on the measurement results. The images are then displayed in real time and saved to a specified folder.

Transfer and backup programs on a PC

Programs created on the CV controller can be easily transferred and saved on a PC. If the contents of the controller get erased, the saved files can be quickly reloaded to the vision system, reducing downtime. If record keeping is essential, all program properties and settings can be output to an Excel* spreadsheet and saved for future reference.

Advanced Data logging

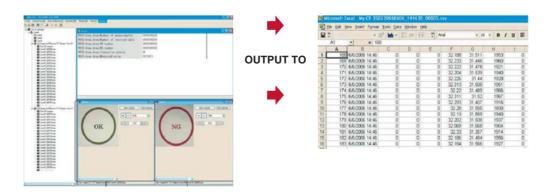
A time-based data log can be set to collect data from various shifts or product runs. Specific pieces of measurement data can also be tied to the corresponding image that was saved on the PC for easy reference.

Data can also be output to a pre-existing Excel* spreadsheet, making the CV data simple to integrate into existing reports.

*Excel is a registered trademark of Microsoft Corporation, U.S.A.







Data is both displayed and saved in real time

COMMUNICATION SOFTWARE

CV-H5N PC Simulator Function

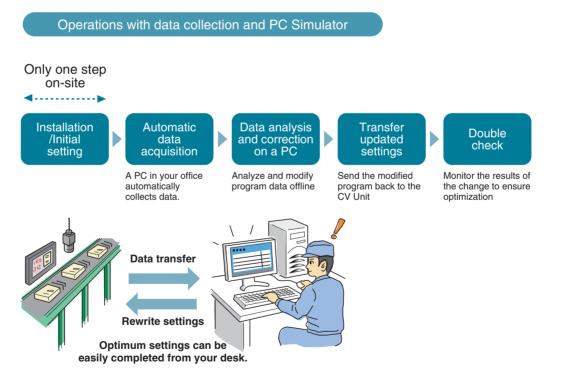
CV SIMULATOR

KEYENCE has added the option of remotely programming the CV from a desktop PC. The CV-H5N PC simulator is designed to precisely mimic the operations of the CV-5002(P)/5502(P)/5702(P) machine vision controllers. All that is needed is a .bmp or .jpg image and it is ready to program!

- Choose to program/troubleshoot directly online (CV controller) or remotely (PC Simulator), providing optimal flexibility
- Transfer programs & images in real time to make remote, offline modifications to an existing CV-5000 Series controller
- Manage CV programs from anywhere in the world!



Both Software Tools in One Package EXAMPLE OF EFFICIENT OPERATION



Multiple Interface Options for Seamless Integration

[FIRST IN THE INDUSTRY]

Save to mass-storage twin SD cards — First in the industry to support the SDHC standard (*). There are 2 available slots for SD cards. With a total capacity of 8GB, a large amount of configuration files and failed screen data can be saved at high speeds.



*Reading SDHC standard SD cards via a PC requires a dedicated card reader (commercially available).

USB 2.0 connector ----

USB 2.0 allows for quick transfer of image data and settings from your PC. No setup necessary. Ready to use on-site.



Illumination control expansion unit --This connector is for the illumination control expansion unit CA-DC20E.

Expansion unit CA-DC20E





Camera connector

The camera cable connection is recessed to minimize dead space when mounted inside control cabinets.



··Camera expansion unit connector

Connects the camera expansion unit CV-E500 when 3 or 4 cameras are used.



Camera expansion unit CV-E500

RS-232C communication Enables a PLC link with PLCs made by other manufacturers. Communicates directly with PLC data memory without

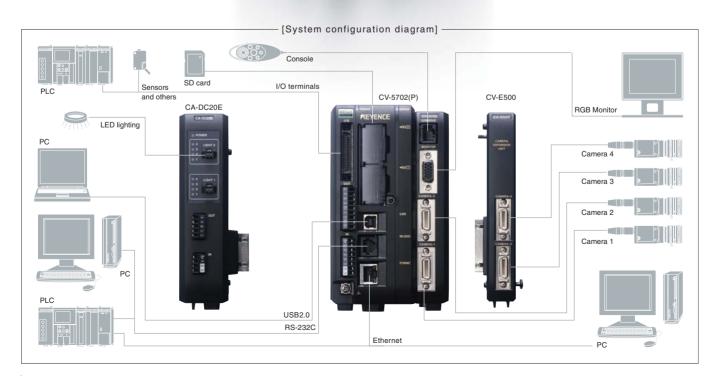
additional ladder programs.



EtherNet/IP Communication

EIP communication is enabled through the Ethernet port so that data can easily be sent to Rockwell PLCs, or other EIP devices.





Product Lineup



Specifications

Controller

Controlle	51	NPN	CV-5702	CV-5502	CV-5002				
Model		PNP	CV-5702P	CV-5502 CV-5502P	CV-5002 CV-5002P				
		When CV-H500C and CV-H50 are connected	OM 5,000,000-pixel mode: 2432 (H) x 2050 (V), about 4,990,000-pixels	-	-				
		When CV-200C/CV-S200C/	2,000,000-pixel mode: 1600 (H) x 1200 (V),	2,000,000-pixel mode: 1600 (H) x 1200 (V),					
lo of nivele		CV-H200C/CV-200M/CV-S200	I,UUU,UUU-pixei mode: 1024 (H) X 960 (V),	about 1,920,000-pixels 1,000,000-pixel mode: 1024 (H) x 960 (V),	-				
lo. of pixels		and CV-H200M are connected	about 980,000 pixels 310,000-pixel mode: 640 (H) x 480 (V),	about 980,000 pixels 310,000-pixel mode: 640 (H) x 480 (V),	310,000-pixel mode: 640 (H) x 480 (V),				
		When CV-035C/CV-S035C/ CV-H035C/CV-035M/CV-S035	about 310,000 pixels	about 310,000 pixels	about 310,000 pixels				
		and CV-H035M are connected		240,000-pixel mode: 512 (H) x 480 (V), about 240,000 pixels	240,000-pixel mode: 512 (H) x 480 (V), about 240,000 pixels				
Camera input			2 color/monochrome cameras (Support for CV-H500C/CV-H200C/CV-200C/CV-200C/CV-035C/ CV-S035C/CV-H035C/CV-H500M/CV-200M/CV- CV-200M/CV-S200M/CV-035M/CV-S035M and CV-H035M possible mixed connection) Connecting expansion unit CV-E500 provides	2 color/monochrome cameras (Support for CV-H200C/CV-200C/CV-200C/CV-35C/ CV-5035(CV-H035C/CV-H200M/CV-200M/ CV-5200M/CV-035M/CV-5035M and CV-H035M possible mixed connection) Connecting expansion unit CV-500 provides	2 color/monochrome cameras (support for CV-035C/CV-S035C/CV-H035C, CV-035M/CV-S035M and CV-H035M possible mixed connection)				
			2-point expansion and connection of up to 4 points	2-point expansion and connection of up to 4 points.					
	sor for image proce ered settings	ssing		-speed type) ard 1 and SD card 2 (depends on memory card capacity ;	DSP				
	creens that can be	registered	1000 screens max./setting (depends on me	mory card capacity), can be compressed and saved, supp	ports registration of position adjusted images				
iternal men	nory capacity			rt) OP-84232 (256MB: Standard equipment on the SD1 s d equipment on the SD1 slot of the CV-5702(P)), CA-SE					
/indow	Measurement area		N	leasurement: 128 windows/program Mask: 4 areas/wind					
etting	Area shape (deper some area shapes	iding on the inspection mode to be are restricted)	used, Rectangle, rotating rectangle, circle	, ellipse, ring, arc, polygon (up to 12 angles), Auto-adjus	sting rectangle, Auto-adjusting circle				
olor extract	tion function (valid	only when a color camera is connec	ted) Color binary, color shade, grey, RGI	3 grey (color corresponds to numeric value specification	with HSB values) 1:n copy supported				
	Area measuremen Position detection		Pattern search (sunnort of multio	Area (color binary, monochrome binary) e detections), pattern sort, edge position, trend edge pos	ition, blob (gravity center position)				
		Edge tool	Edge widt	h, edge pitch, No. of edges, edge angle, pair edge, trend	edge width				
		Feature inspection		principal axis angle, area, ferret diameter, circumference etection through combined use with the differential filter, d					
leasurement ool		Stain/inspection	(hole-filling enable/disable sel	ectable), and stability display, support for directly measuri	ng color images with fine color)				
	Inspection mode	Sorting Shade inspection	Shade instr	Pattern sort (256 types max.) ection, color inspection (valid only when a color camera	is connected)				
		Geometry	Display of	points, lines, and circle areas where the operation result	can be cited				
		Character recognition Trend edge defect		maximum, 20 characters/line) Supports date/time encry e inspection using a line, circle, arc, or freeform referenc					
	capture function		1-to-32-times continuous capture processing (maximum	value, minimum value, average value), possible exclusion o	f the measurement error value from the measurement				
xecution co	ndition setting fund	tion		works with the measurement judgment results (OK/NG) x 960 (V)) in any position as the processing area within					
nage	Processing area s	etting function	1,920,000 pixels (1,000,000-pixel mode). Enables yo	u to specify a 240,000-pixel area (512 (H) x 480 (V)) or	480 (V)) or 310,000-pixel area (640 (H) x 480 (V) in				
apturing etting	Scan mode (valid or	ly when a monochrome camera is conn		tion as the processing area within 320,000 pixels.*1 Progressive/interlace switching	position as the processing area within 320,000 pixels				
inction		d line setting function	Enables you to set any capturing start/en	d line within the image capturing range (for interlace, this	s specification is made in units of 2 lines).				
	Position adjustment			ou must specify at least 100 lines when using CV-H200C /individual adjustments (up to 128 settings), X, Y, 180°					
	Camera gain adjustment		Camera sensitivity adjustment, offset adjustment, span ad	justment (supports settings in 16 tone levels; also supports					
orrection	White balance adjustment (valid only when a color camera is connected) Image inversion function		ected)	Manual setting with white paper Support of left/right inversion for image capture					
unctions		Count		9-time repetition for the same type, 13 levels (for binary and difference, 1 level/window) Expansion, shrink, averaging, median, edge enhancement, edge extraction X, edge extraction Y, Sobel, Prewitt, Roberts, Laplacian, binary, difference,					
	Filter function	Туре		nhancement, edge extraction X, edge extraction Y, Sobel ment, contrast conversion, image extraction, real-time sh					
	Numerical	No. of settings		128 calculation /program					
Calculation unction	operation	Туре	Four arithmetic operations, arithmetic function, o logical opera	comparison operator, geometric calculation function, coc tor, journalizing function, system function, time axis ope	ration function				
	Command memor			nd memories are installed from the external devices and					
	Statistics analysis No. of Statistical items		Up to 20000 data points (support of batch save to n Internal memory: Up to 1023 screens/1020 screens (240,000-pixel mode) Up to 511 screens/509 screens (310,000-pixel mode)	nemory card) Maximum value, minimum value, average Internal memory: Up to 511 screens/508 screens (240,000-pixel mode)	Internal memory: Up to 511 screens/508 screer				
	Screen save (valid when monochrome and color cameras are connected)		Up to 255 screens/252 screens (1,000,000-pixel mode) Up to 127 screens/124 screens (2,000,000-pixel mode) Up to 50 screens/137 screens (500,0000-pixel mode). (Maximum value when one monorthrome camera and one color camera are connected and the accumulation condition is "AII")	Up to 255 screens/253 screens (310,000-pixel mode) Up to 127 screens/124 screens (1,000,000-pixel mode) Up to 63 screens/60 screens (2,000,000-pixel mode). (Maximum value when one monochrome camera and one color camera are connected and the accumulation condition is "All")	(240,000-pixel mode) Up to 255 screens/253 screens (310,000-pixel mod (Maximum value when one monochrome camera one color camera are connected and the accumula condition is "All")				
	Programming aid	Display aid		differentiation waveform display, profile display, stain sta ect level waveform display of trend edge defects during s					
upport	functions	Batch move	Enables you to	collectively move selected windows in X and Y direction	ns during setup.				
inctions		No. of display templates No. of screens that can be displayed simulta		i the 10 patterns, 4 patterns are the specified values) Pos ay up to 5 screens (when 5-screen horizontal splitting or					
	setting function	Hold image	Past images (NG images) can be displayed as h	old images (up to 3 times before). The measurement res camera connection status, the displayable count change	ult and measurement time can also be referenced				
	Screen customization function	No. of customized screens		g : Measured value, judgment result, optional character, f					
	Custom menu fun Operation rewrite			create a shortcut menu to an optional setting screen (20 d command memories during operation. Supports light dimr					
		function (SD2 slot only)	Supports measured values, judgment results, NG	count, measurement images (can be compressed and say	ved), saved images (can be compressed and saved),				
	Others			, settings (settings can also be saved to the SD1 slot) and retest function, file management function, I/O monitor, F					
	00003		2 points, simultaneous 2-camera capturing or individual capturing	selectable, EV support, input rating: 26.4 V max., 3 mA min. Individu	al trigger delays can be set (from 0 to 999 ms) for each trigger				
	Control input	External trigger input	Simultaneous capturing of up to 4 car (If CV-E500 is not connected up to 2 monochrom	neras or individual capturing selectable e or color cameras can be simultaneously captured.)	Simultaneous capturing of up to 2 cameras o individual capturing selectable				
		Control input		18 points, input rating: 26.4 V max., 2 mA min.	· · · ·				
	Control output	Universal output Total comparator output		tput points that work with an external trigger), NPN open N open collector, 50 mA max. (30 V max.) Hold time sett					
terface	Monitor output			Analog RGB output, SVGA 800 x 600 (24-bit color, 60 H	z)				
	Run indicator		RS-232C (maximum baud rate: 1152	LED display that works with power supply/ERROR output 00 bps//Ethernet (1000BASE-T/100BASE-TX/10BASE-T a (compressed output available), control I/O available, si)/ USB (USB2.0 HI-SPEED supported)				
	Communication port	PLC link	Numerical input/output data using the RS-232 or Ethe A*2/Q/L series of Mitsubishi Electric Corporation;	ernet port and control I/O. Simultaneous use of the Ethern SYSMAC C series* ² and CS1/CJ1/CJ2 series of Omron	net (TCP/IP) and USB ports available. Supported PL Corporation; MP900 series* ² and MP2000 series o				
		EtherNet/IP		Connection via link unit and used exclusively from Ether the Ethernet port. Supports implicit and explicit message					
isplay langı				Japanese/English/German selectable	× ,				
umination	control Power supply volt	906	LED light ON/OFF control (12 V, 24 V) and dimmer control supported who	en optional Light Controller Unit CA-DC20E is connected. Connect up to 2ch 24 VDC ±10%	n/controller, max. 4 controllers. Supports multiple lighting pattern fu				
ating	Current consumpt			, 3.2 A (4-camera connection and maximum load)	2.2 A (2-camera connection and maximum loa				
				1,000,000-pixel or higher camera connection:	0 to 50°C 32 to 122°F				
	Ambient temperat	ure	() to 45°C 32 to 113°F Alcomora	CONDECTION: U TO 45"U 32 TO 113"F					
invironmental esistance Veight	Ambient temperat Relative humidity		0 to 45°C 32 to 113°F 4-camera	35 to 85%, No condensation Approx.1250 g					

*1: Not selectable when CV-H035C/CV-H035M is connected as the pixel area is 310,000 (640 (H) x 480 (V)). *2: Only the RS-232C port is supported.

Camera (CV-H500C/H500M/H200C/H200M)

Model		Camera (CV-H500C/CV-H500M) ^{*3} Camera (CV-H200C/CV-H200M) ^{*3}			
Image receiving element		2/3-inch color CCD image receiving element, 11x high-speed reading using, square-pixel, 5,050,000 pixels (CV-H500C) 2/3-inch monochrome CCD image receiving element, 11x high-speed reading using, square-pixel, 5,050,000 pixels (CV-H500M) Unit cell size 3.45 x 3.45 µm 0.14 x 0.14 Mil	 1/1.8-inch color CCD image receiving element, 7x high-speed reading using, square-pixel, 2,010,000 pixels (CV-H200C) 1/1.8-inch monochrome CCD image receiving element, 7x high-speed reading using, square-pixel, 2,010,000 pixels (CV-H200M) Unit cell size 4.4 x 4.4 µm 0.17 x 0.17 Mil 		
Number of valid pi	ixels	4,990,000 pixels 2432 (H) x 2050 (V) 1,920,000 pixels 1600 (H) x 1200 (V) ^{*4}			
Scanning system		Progressive (61.2 ms) Progressive (29.2 ms: 2,000,000-pixel mode 24.2 ms: 1,000,000-pixel mode) Interlace: CV-H500M only (40.3 ms) Interlace: CV-H200M only (16.1 ms: 2,000,000-pixel mode 13.6 ms: 1,000,000-pixel mode			
Pixel transfer frequ	uency	130 MHz (65 MHz x 2 ch) 82 MHz (41 MHz x 2 ch)			
Transfer system		Digital serial transfer			
Electronic shutter		1/15, 1/30, 1/60, 1/120, 1/240, 1/500, 1/1000, 1/2000, 1/5000, 1/100	000, 1/20000, 0.05 msec to 9000 msec can be set with numeric values		
Lens mount metho	bd	C mount			
Environmental	Ambient temperature	0 to 40°C 32 to 104°F			
resistance	Relative humidity	35 to 85%, No	o condensation		
Weight		Approx. 130 g (not including lens)			

*3: Only the high-speed camera cable can be used.
 *4: In 1,000,000-pixel mode, 980,000 pixels (1024 x 960) serve as the processing area.

Camera (CV-H035C/H035M)

Model		Camera (CV-H035C/CV-H035M) *5	
Image receiving element 1/3-inch m		1/3-inch color CCD image receiving element, 7x high-speed reading using square-pixel, 340,000 pixels (CV-H035C) 1/3-inch monochrome CCD image receiving element, 7x high-speed reading using square-pixel, 340,000 pixels (CV-H035M) Unit cell size: 7.4 x 7.4 μm 0.29 x 0.29 Mil	
Number of valid pix	els	310,000 pixels 640 (H) × 480 (V) ^{*6}	
Scanning system Progressive (4.7 ms) Interlace: CV-H035M only (2.5 ms)			
Pixel transfer freque	ency	80 MHz 40 MHz × 2ch	
Transfer system		Digital serial transfer	
Electronic shutter		1/15, 1/30, 1/60, 1/120, 1/240, 1/500, 1/1000, 1/2000, 1/5000, 1/10000, 1/20000, 0.05 msec to 9000 msec can be set with numeric values.	
Lens mount method	1	C mount	
Environmental Ambient temperature 0 to 40°C 32 to 104°F		0 to 40°C 32 to 104°F	
resistance	Relative humidity	35 to 85%, No condensation	
Weight		Approx. 120 g (not including lens)	

*5: Only the high-speed camera cable can be used.
*6: In 310,000-pixel mode, 310,000 pixels (640 x 480) serve as the processing area. In 240,000-pixel mode, 240,000 pixels (512 x 480) serve as the processing area.

Camera (CV-200C/200M/S200C/S200M)

Model		Camera (CV-200C/CV-200M) *7	Camera (CV-S200C/CV-S200M) *7		
Image receiving element		1/1.8 -inch color CCD image receiving element, square-pixel/all-pixel reading, 2,010,000 pixels (CV-200C)	1/1.8 -inch color CCD image receiving element, square-pixel/all-pixel reading, 2,010,000 pixels (CV-S200C)		
		1/1.8 -inch monochrome CCD image receiving element, square-pixel/all-pixel reading, 2,010,000 pixels (CV-200M) Unit cell size: 4.4 x 4.4 μm 0.17 x 0.17 Mil	1/1.8 -inch monochrome CCD image receiving element, square-pixel/all-pixel reading, 2,010,000 pixels (CV-S200M) Unit cell size: 4.4 x 4.4 μm 0.17 x 0.17 Mil		
Number of valid pix	xels	1,920,000 pixels 16	600 (H) x 1200 (V) ^{*8}		
Scanning system		Progressive (58.5 ms: 2,000,000-pixel mode, 47.6 ms: 1,000,000-pixel mode) Progressive (58.5 ms: 2,000,000-pixel mode, 47.6 ms: 1,000,000-pixel mode) Interlace: CV-200M only (32.7 ms: 2,000,000-pixel mode, 27 ms: 1,000,000-pixel mode)			
Pixel transfer frequ	Pixel transfer frequency 40 MHz		MHz		
Transfer system		Digital ser	rial transfer		
Electronic shutter		1/15, 1/30, 1/60, 1/120, 1/240, 1/500, 1/1000, 1/2000, 1/5000, 1/100	000, 1/20000, 0.05 msec to 9000 msec can be set with numeric values.		
Lens mount metho	d	C mount	Special mount (M15.5 P0.5 male)		
Environmental	Ambient temperature	0 to 40°C 32 to 104°F	Head: 0 to 40°C 32 to 104°F, relay unit: 0 to 40°C 32 to 104°F		
resistance	Ambient temperature	01040 0 32 10 104 1	(however, 35°C 95°F max. in partial capturing 50 lines or lower)		
16313101166	Relative humidity	35 to 85%, No	p condensation		
Weight		Approx. 110 g (not including lens)	Head: Approx. 210 g (including the cable, not the lens), relay unit: Approx. 70 g		

*7: The CA-CN17 camera cable (17 m) 55.8' and the CA-CN17R high-flex camera cable (17 m) 55.8' cannot be used. *8: In 1,000,000-pixel mode, 980,000 pixels (1024 x 960) serve as the processing area.

Camera (CV-035C/035M/S035C/S035M)

Model		Camera (CV-035C/CV-035M) Camera (CV-S035C/CV-S035M) ^{*9}			
Image receiving element		 1/3 -inch color CCD image receiving element, 2x high-speed reading using square-pixel, 350,000 pixels (CV-035C) 1/3 -inch monochrome CCD image receiving element, 2x high-speed reading using square-pixel, 350,000 pixels (CV-035M) Unit cell size: 7.4 x 7.4 µm 0.29 x 0.29 Mil 	 1/3 -inch color CCD image receiving element, 2x high-speed reading using square-pixel, 350,000 pixels (CV-S035C) 1/3 -inch monochrome CCD image receiving element, 2x high-speed reading using square- pixel, 350,000 pixels (CV-S035M) Unit cell size: 7.4 x 7.4 µm 0.29 x 0.29 Mi 		
Number of valid pi	ixels	320,000 pixels 65	i6 (H) x 492 (V) ¹⁰		
Scanning system		Progressive (16 ms) Progressive (16 ms) Interlace: CV-035M only (8.8 ms) Interlace: CV-S035M only (8.8 ms)			
Pixel transfer frequ	uency	24.5 MHz			
Transfer system		Digital serial transfer			
Electronic shutter		1/15, 1/30, 1/60, 1/120, 1/240, 1/500, 1/1000, 1/2000, 1/5000, 1/100	000, 1/20000, 0.05 msec to 9000 msec can be set with numeric values.		
Lens mount metho	bd	C mount	Special mount (M10.5 P0.5 male)		
Environmental Ambient temperature		0 to 50°C 32 to 122°F	Head: 0 to 50°C 32 to 122°F, relay unit: 0 to 40°C 32 to 104°F		
resistance	Relative humidity	35 to 85%, No	o condensation		
Weight		Approx. 100 g (not including lens)	Head: Approx. 160 g (including the cable, not the lens), relay unit: Approx. 70 g		

*9: The CA-CN17 camera cable (17 m) 55.8' and the CA-CN17R high-flex camera cable (17 m) 55.8' cannot be used. *10: In 310,000-pixel mode, 310,000 pixels (640 x 480) serve as the processing area. In 240,000-pixel mode, 240,000 pixels (512 x 480) serve as the processing area.

Dimensions

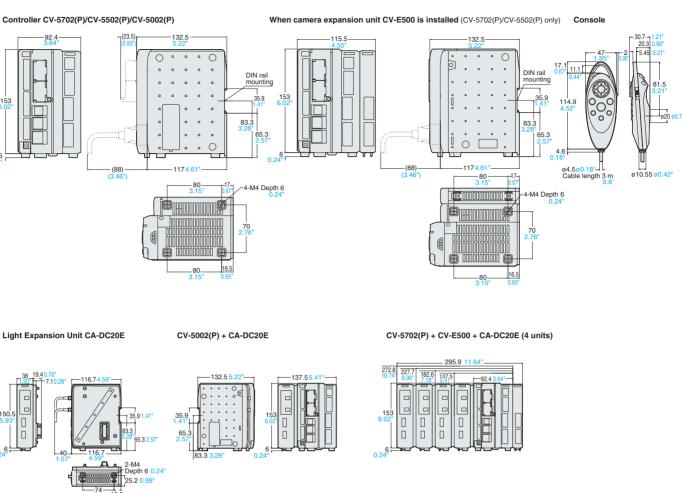
153

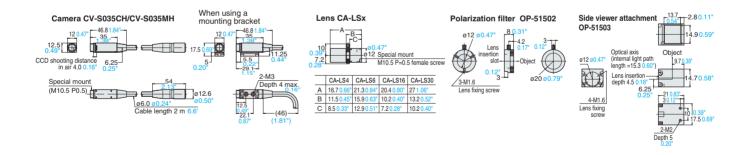
6 0.24"

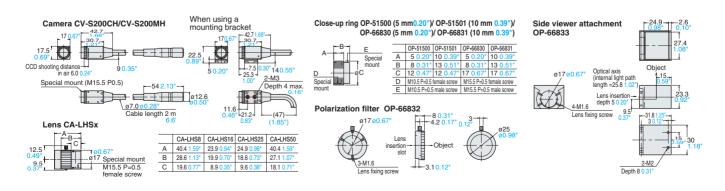
150.

0.2⁴

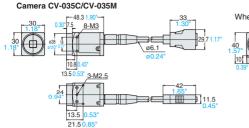
16.5

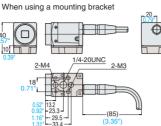




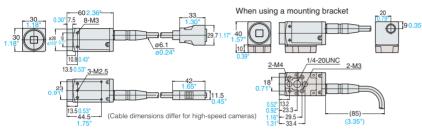


30





Camera CV-H500C/CV-H500M/CV-H200C/CV-H200M/CV-200C/CV-200M/CV-H035C/CV-H035M



Camera cable

CA-CN1 (1 m) 3.3' / CA-CN3 (3 m) 9.8' / CA-CN5 (5 m) 16.4' / CA-CN10 (10 m) 32.8' / CA-CN17 (17 m) 55.8' High-flex camera cable

CA-CN3R (3 m) 9.8' / CA-CN5R (5 m) 16.4' / CA-CN10R (10 m) 32.8' / CA-CN17R (17 m) 55.8'

Cable dedicated for high-speed cameras CA-CH3 (3 m) 9.8' / CA-CH5 (5 m) 16.4' / CA-CH10 (10 m) 32.8'

High-flex cable dedicated for high-speed cameras CA-CH3R (3 m) 9.8' / CA-CH5R (5 m) 16.4' / CA-CH10R (10 m) 32.8'

øA B	

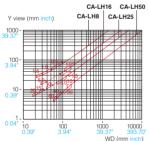
Cable length (1 m 3.3', 3 m 9.8', 5 m 16.4', 10 m 32.8', 17 m 55.8')

	A	В	С	D	E	F
CA-CNx	12.5 0.49*	43 1.69"	6.1 0.24*	42 1.65"	331.30"	29.7 1.17
CA-CNxR	14.0 0.55*	54 2.13"	6.6 0.26*	42 1.65"	331.30"	29.7 1.17
CA-CHx	12.5 0.49*	43 1.69"	7.2 0.28"	41 1.61"	31 1.22*	31.4 1.24"
CA-CHxR	14.0 0.55*	54 2.13"	7.6 0.30"	41 1.61"	31 1.22"	31.4 1.24"

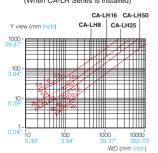
Lens Selection Charts CV-H200C/CV-H200M

CV-200C/CV-200M

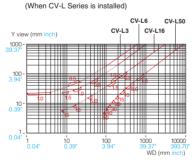
(When CA-LH Series is installed)



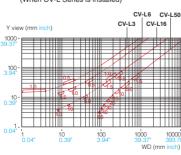
CV-035C/CV-035M CV-H035C/CV-H035M (When CA-I H Series is installed)

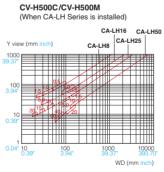


CV-H200C/CV-H200M CV-200C/CV-200M

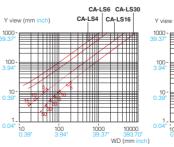


CV-035C/CV-035M CV-H035C/CV-H035M (When CV-L Series is installed)

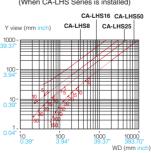




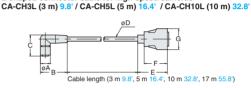
CV-S035C/CV-S035M (When CA-LS Series is installed)



CV-S200C/CV-S200M (When CA-LHS Series is installed)



Values in the table are merely reference values; adjustments may be required during installation



L-shaped connector cable for high-speed cameras

CA-CN3L (3 m) 9.8' / CA-CN5L (5 m) 16.4' / CA-CN10L (10 m) 32.8' / CA-CN17L (17 m) 55.8'

Camera Control Unit CV-S200CU/CV-S200MU/

0.14".3

With cable connected

Controller side

(76) (2 0

L-shaped connector camera cable

0.24

33

ø6.1

11.5

29.

CV-S035CU/CV-S035MU

-3.5 0.14"

26 1 02

_ı 2-ø3.6 through hole ø0.14

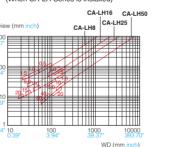
6 210.83

Camera side

2-ø3.6 through hole ø0.14

11.5

	Α	В	С	D	E	F	G
L-shaped connector camera cable CA-CNxL	14	38	30	6.1	42	33	29.7
	0.55"	1.50"	1.18"	<mark>0.24</mark> "	1.65"	<mark>1.30</mark> "	1.17"
L-shaped connector cable for	14	38	30	7.2	41	31	31.4
high-speed cameras CA-CHxL	0.55"	1.50"	1.18"	<mark>0.28</mark> "	1.61"	1.22"	1.24"



CV-5000 SERIES

All-in-One Image Processing CV-700 Series

CE



Simple, Straightforward Programming Designed for Easy Operation

Simple Programming helps for quick and efficient on-site operation, reducing set-up costs.



Features

- Color and Grayscale processing for any application
- Built-in monitor and 2 camera connectivity for easy integration
- Simple touch panel user interface

The All-in-One Design Saves Space and Reduces Wiring

The CV-751 comes standard with a built-in 5.5" TFT color monitor and an array of on-board I/O options, such as discrete, analog, and RS-232 communications. The system can be configured via a remote console or a built-in touch panel.

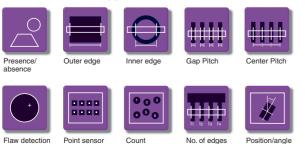
High-Speed Search & Sub-pixel Measurement

Special ASIC technology ensures accurate measurement by using sub-pixel processing and a fast 360° rotation search.

Comprehensive menus

Menus are available for nearly every in-line need. Up to 8 different inspection modes can be combined in a single program.

Applications Menu



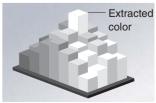
The principle of color Shade-Scale processing

Color Shade-Scale processing recognizes the differences in hue and intensity of shade levels.

After clicking on a target to extract its color, the entire image is converted to a shade hierarchy with the extracted color as the top level.



Click on the target point for color extraction.



The whole image is converted into a gray shade image with the extracted color as the top level.

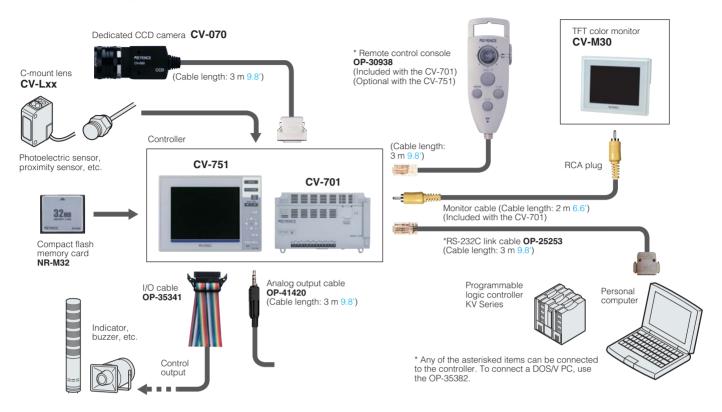
Controller

Туре				Built-in monitor type	Separate monitor type						
Type				CV-751(P)	CV-701(P)						
				*Input with a remote control console (optional) is also available.							
Model											
No. of pixel				508 (H) × 480 (V)							
Process cyc	cle			30 c/s (Varies depending on the setting)							
Binary level	l			Color binary processing by color extraction or color shade processing Color can be specified individually for each window							
Program re	<u> </u>			16 programs (8 programs when two cameras are used) (Programs are externally selectable)							
No. of regis	stered screens	1		16 screens (1 screen/program or 2 screens/program)							
		Area sensor		8 max./program, Window shape: Circle/square/free square							
		Absolute position detection Relative position detection		4/program, Window shape: Square							
		Relative pos	1	4/program, Window shape: Square 8/program, Window shape: Square							
			Width measurement Pitch measurement								
	Mode			8/program, Window shape: Square							
		Inspection	Edge count Count	8/program, Window shape: Square							
		mode	Flaw detection	8/program, Window shape: Square/circle 8/program, Window shape: Square/circle/ring/arc							
			Point sensor								
			Center-of-gravity	8/program, 8 points/Window 8/program, Window shape: Square/circle							
Functions		Position adj	,	Color shade search/Line sensor/Color binary processing (Center of gravity, Major axis inclination, X-Y-axis direction, ±180° rotation)							
	Adjustment	Illumination	adjuatment								
	Adjustment	Illumination adjustment		1 illumination adjustment window/program (two when two cameras are connected) Expand. Shrink. Median. Average. Edge enhancement.							
		Pre-process	sing (Filter function)	Edge detection, Shading, Lightness-up, Saturation-up, Invert							
	Auto-sequence			Continuous processing of 4 programs max. (Up to 32 inspections [4 programs x 8 windows] can be continuously processed)							
	Data calcula			Unit conversion and offset							
	Screen save			8 screens							
	Setup menu			Stores parameters of initial setting							
	Camera inp	1		2 1 (Non-voltage input)							
		External trig		1 (Non-voltage input)							
Input	Orinteral	Program se	IECUOII	Data input (x4), 16 programs selectable (Non-voltage input)							
Input	Control input	Continuous		Detection continued without an external trigger when the program No. is changed while CONT input is ON. (Non-voltage input)							
		Screen regis		2, Screen is registered by a trigger signal v							
	Panel	Display/outp	out window selection	TFT 5.5 inch, full color	selectable (Non-voltage input)						
LCD monitor	Backlight			Cold cathode fluorescent tube	Not provided Not provided						
Momonusa	rd			(Average line: Approx. 40000 lins)							
Memory ca				Compact Flash memory Conforms to NTSC standards							
Video output RS-232C interface				Contorms to NISC standards 1 ch, Numerical value output and control input/output (Baud rate: 38400 bps max. selectable)							
NPN				NPN open-collector: 9, 50 mA max. (30 V max.)							
Control output PNP				PNP open-collector: 9, 50 mA max. (30 V max.)							
Numerical value output				Binary 13 bits, 10 mA max. (30 V max.)							
Analog output				0 to 4 V output, Output impedance: 100 Ω							
Display language				English/Japanese selectable							
Power supp	<u> </u>			24 VDC±10%							
Current cor				1.4 A 700 mA							
Ambient temperature				0 to 40°C 32 to 104°F, No freezing							
Relative humidity				35 to 85%, No condensation							
Weight				Controller: Approx. 900 g	Controller: Approx. 400 g, Remote control console: Approx. 160 g						

Camera

Туре	CV-070
Image pickup element	1/3 inch CCD video element, Square-pixel all reading
Electronic shutter	1/30, 1/50, 1/60, 1/100, 1/125, 1/250, 1/500, 1/1000, 1/2000, 1/4000, 1/10000
Lens mount method	C mount
Ambient temperature	0 to 40°C 32 to 104°F, No freezing
Relative humidity	35 to 85%, No condensation
Weight	Camera: Approx. 310 g (including 3-m 9.8' cable)

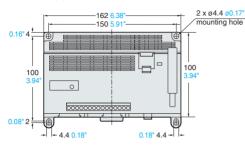
System Configurations

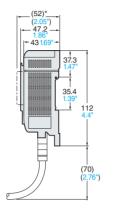


Dimensions

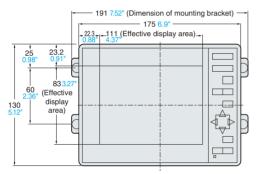
Unit: mm inch

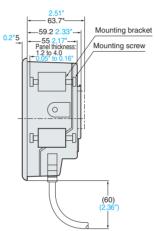
Controller CV-701(P)



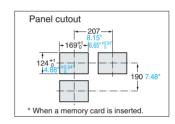


Controller CV-751(P)

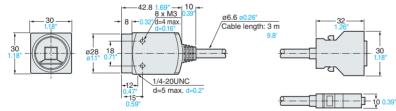


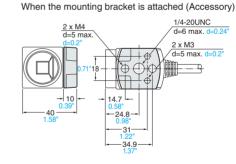


30

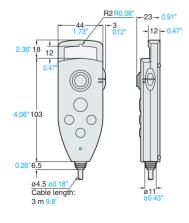


Camera CV-070





Remote control console (OP-30938)



CV-700 SERIES



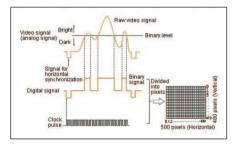
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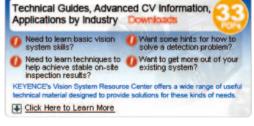
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